

# numerical radiative transfer I

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# Overview

- The problem
- Numerical solution
- Examples
- Outlook

# The Problem

- radiation transport in moving media
- → co-moving frame approach
- advantage: all opacities simple to compute
- → fast & easy
- but: additional terms in the RTE

# Radiative Transfer

$$e \frac{\partial I}{\partial r} + \frac{\partial}{\partial \mu} (fI) + g \frac{\partial}{\partial \lambda} (\lambda I) + hI = \eta - \chi I$$

with

$$e(r, \mu) = \gamma(\mu + \beta)$$

$$f(r, \mu) = \gamma(1 - \mu^2) \left[ \frac{1 + \beta\mu}{r} - \gamma^2(\mu + \beta) \frac{\partial \beta}{\partial r} \right]$$

$$g(r, \mu) = \gamma \left[ \frac{\beta(1 - \mu^2)}{r} + \gamma^2 \mu(\mu + \beta) \frac{\partial \beta}{\partial r} \right]$$

$$h(r, \mu) = \gamma \left[ \frac{\beta(1 - \mu^2)}{r} + \gamma^2(1 + \mu^2 + 2\beta\mu) \frac{\partial \beta}{\partial r} \right]$$

# Radiative Transfer

- $I(r, \mu, \lambda)$ : specific intensity scaled by  $r^2$ ,
- $r$ : radial coordinate,
- $\mu$ : cosine of the direction angle,  $\mu = \cos \phi$
- $v$ : velocity,  $\beta = v/c$ ,  $\gamma^2 = 1/(1 - \beta^2)$ ,
- $\chi(r, \lambda)$ : extinction coefficient,  $\chi = \kappa + \sigma_e + \kappa_l \varphi(\lambda)$
- $\eta(r, \lambda)$ : emissivity.

# Radiative Transfer

Example for  $\eta(r, \lambda)$

$$\eta = \kappa B_\lambda(T) + \sigma_e J(\lambda) + \kappa_l \varphi(\lambda) \int_0^\infty \varphi(\lambda) J(\lambda) d\lambda$$

with

$$J(\lambda) = \int_{-1}^1 I(\lambda) d\mu$$

- $\kappa B_\lambda(T)$ : thermal emission
- $\sigma_e J(\lambda)$ : electron scattering
- $\frac{\sigma}{2} \int_0^\infty \int_{-1}^1 \varphi(\lambda) I d\mu d\lambda$ : spectral line emissivity

# Numerical solution

- recap: scattering  $\rightarrow$

$$S = (1 - \epsilon)J + \epsilon B$$

$$\epsilon = \frac{\kappa}{\kappa + \sigma}$$

- $S$  depends on  $B$  and (unknown)  $J$
- $\rightarrow$  self-consistent solution for  $J$  required
- direct solution expensive
- use iterative method
- eigenvalues of iteration matrix close to unity  
 $\rightarrow$  use operator splitting to reduce eigenvalues of amplification matrix

# Operator Splitting in RT

- Formal solution (how? see below!)

$$J = \Lambda S$$

- $\Lambda$ -iteration:

$$\bar{J}_{\text{new}} = \Lambda S_{\text{old}}, \quad S_{\text{new}} = (1 - \epsilon)\bar{J}_{\text{new}} + \epsilon B$$

- does *not* work for  $\tau \gg 1$  & small  $\epsilon$

# Operator Splitting in RT

- Solution: Split  $\Lambda$  operator

$$\Lambda = \Lambda^* + (\Lambda - \Lambda^*)$$

- $\rightarrow$  iteration procedure

$$\bar{J}_{\text{new}} = \Lambda^* S_{\text{new}} + (\Lambda - \Lambda^*) S_{\text{old}}$$

# Operator Splitting in RT

• using

$$S = (1 - \epsilon)J + \epsilon B$$

and

$$\bar{J}_{\text{fs}} = \Lambda S_{\text{old}}$$

• gives

$$[1 - \Lambda^*(1 - \epsilon)] \bar{J}_{\text{new}} = \bar{J}_{\text{fs}} - \Lambda^*(1 - \epsilon) \bar{J}_{\text{old}}$$

# Operator Splitting in RT

- solved directly to obtain  $\bar{J}_{\text{new}}$

$$\bar{J}_{\text{new}} = [1 - \Lambda^*(1 - \epsilon)]^{-1} (\bar{J}_{\text{fs}} - \Lambda^*(1 - \epsilon)\bar{J}_{\text{old}})$$

# Operator Splitting in RT

- mathematically:
- same family as Jacobi or Gauss-Seidel methods
- general form

$$Mx^{k+1} = Nx^k + b$$

for solution of linear system

$$Ax = b$$

with

$$A = M - N$$

# Operator Splitting in RT

- operator splitting  $\rightarrow$

$$M = 1 - \Lambda^*(1 - \epsilon)$$

and

$$N = (\Lambda - \Lambda^*)(1 - \epsilon)$$

for the system matrix

$$A = 1 - \Lambda(1 - \epsilon)$$

# Operator Splitting in RT

- convergence of the iterations  $\rightarrow$
- spectral radius  $\rho(G) < 1$
- with amplification matrix

$$G = M^{-1}N$$

# Operator Splitting in RT

- for this to help
  - eigenvalues of amplification matrix  $G \ll 1$
  - works best if  $\Lambda^* = \Lambda$  (direct solution, how? see below!)
  - $\rightarrow$  expensive (?)
  - diagonal  $\Lambda^* \rightarrow$   
simple but slow convergence
  - band-matrix  $\Lambda^* \rightarrow$   
rapid convergence, harder to construct

# Operator Splitting in RT

- many possible ways to construct  $\Lambda^*$
- best: elements of  $\Lambda$  itself
  - no estimates/free parameters
  - 'easy' to compute & use
  - build band-matrix  $\Lambda^*$

# Formal Solution

- pp RTE:

$$\mu \frac{dI}{d\tau_r} = I - S$$

- discretize  $\tau_r$  (spatial) space
- discretize  $\mu$  (angle) space
- light path  $\rightarrow$  lines of constant  $\mu$

# Formal Solution

- → characteristics of the RTE
- along a characteristic

$$\frac{dI}{d\tau} = I - S$$

- where  $I = I(\mu)$  and  $\tau = \tau_r/\mu$  are now measured along the characteristic

# Formal Solution

- spherical geometry:

$$\mu \frac{\partial I}{\partial r} + \frac{1 - \mu^2}{r} \frac{\partial I}{\partial \mu} = \chi(S - I)$$

- characteristics = light paths
- static medium  $\rightarrow$  straight lines
- parameterized by *impact parameter*  $p$

$$\mu(r) = \pm \sqrt{1 - p^2/r^2}$$

gives  $\mu$  for each point along the characteristic  $p$

# Formal Solution

- → along a characteristic  $\mu$  varies in spherical geometry
- but the RTE along the characteristic looks like

$$\frac{dI}{d\tau} = I - S$$

- where  $I = I(\mu(p))$  and  $\tau$  are now measured along the characteristic

# Formal Solution

- → spherical and pp cases reduced to FS along the characteristic
- $J$  computed by numerical quadrature
- need to compute  $I$  along the characteristics
- basic idea:
  - approximate  $S$  along the characteristic by piece-wise linear or parabolic functions
  - analytically solve FS along the characteristic for  $I$

# Formal Solution

- this scheme gives

$$I(\tau_i) = I(\tau_{i-1}) \exp(\tau_{i-1} - \tau_i) + \int_{\tau_{i-1}}^{\tau_i} S(\tau) \exp(\tau - \tau_i) d\tau$$

$$I(\tau_i) \equiv I_{i-1} \exp(-\Delta\tau_{i-1}) + \Delta I_i$$

- $\tau_i$  denotes the optical depth along the ray with  $\tau_1 \equiv 0$  and  $\tau_{i-1}$
- $\tau$  is calculated using piecewise linear interpolation of  $\chi$  along the ray

$$\Delta\tau_{i-1} = (\chi_{i-1} + \chi_i) |s_{i-1} - s_i| / 2$$

# Formal Solution

- $S(\tau)$  along a characteristic is interpolated by linear or parabolic polynomials so that

$$\Delta I_i = \alpha_i S_{i-1} + \beta_i S_i + \gamma_i S_{i+1}$$

with

$$\begin{aligned}\alpha_i &= e_{0i} + [e_{2i} - (\Delta\tau_i + 2\Delta\tau_{i-1})e_{1i}] / [\Delta\tau_{i-1}(\Delta\tau_i + \Delta\tau_{i-1})] \\ \beta_i &= [(\Delta\tau_i + \Delta\tau_{i-1})e_{1i} - e_{2i}] / [\Delta\tau_{i-1}\Delta\tau_i] \\ \gamma_i &= [e_{2i} - \Delta\tau_{i-1}e_{1i}] / [\Delta\tau_i(\Delta\tau_i + \Delta\tau_{i-1})]\end{aligned}$$

for parabolic interpolation and

# Formal Solution

$$\begin{aligned}\alpha_i &= e_{0i} - e_{1i}/\Delta\tau_{i-1} \\ \beta_i &= e_{1i}/\Delta\tau_{i-1} \\ \gamma_i &= 0\end{aligned}$$

for linear interpolation.

• auxiliary functions:

$$\begin{aligned}e_{0i} &= 1 - \exp(-\Delta\tau_{i-1}) \\ e_{1i} &= \Delta\tau_{i-1} - e_{0i} \\ e_{2i} &= (\Delta\tau_{i-1})^2 - 2e_{1i}\end{aligned}$$

# Formal Solution

- $\Delta\tau_i \equiv \tau_{i+1} - \tau_i$  is the optical depth along the characteristic
- must use linear coefficients at the last integration point along each ray
- some times linear may be better than parabolic (why?)

# Formal Solution

- spherical case:
  - tangent rays: FS starts at point 2 with  $I_1$  given as the outer BC and proceeds along the ray
  - FS for 'core-intersecting' ray: split into two parts:
    1. integration from point 1 to point  $N$ , where  $I_1$  is given as the outer boundary condition and
    2. integration from point  $N + 2$  to point  $2N$ , where  $I_{N+1}$  is given as the inner boundary condition.
- pp case: like 'core intersecting' spherical case

# Formal Solution

- with this procedure, the  $I$ 's can be computed for given  $S$
- for all characteristics  $\rightarrow$  full RF is known
- could be used for  $\Lambda$  iteration for  $\epsilon \approx 1$
- next step: devise procedure to compute  $\Lambda^*$ !
- space-discretized  $\rightarrow$   
 $\Lambda$  operator  $\rightarrow$   $\Lambda$  matrix

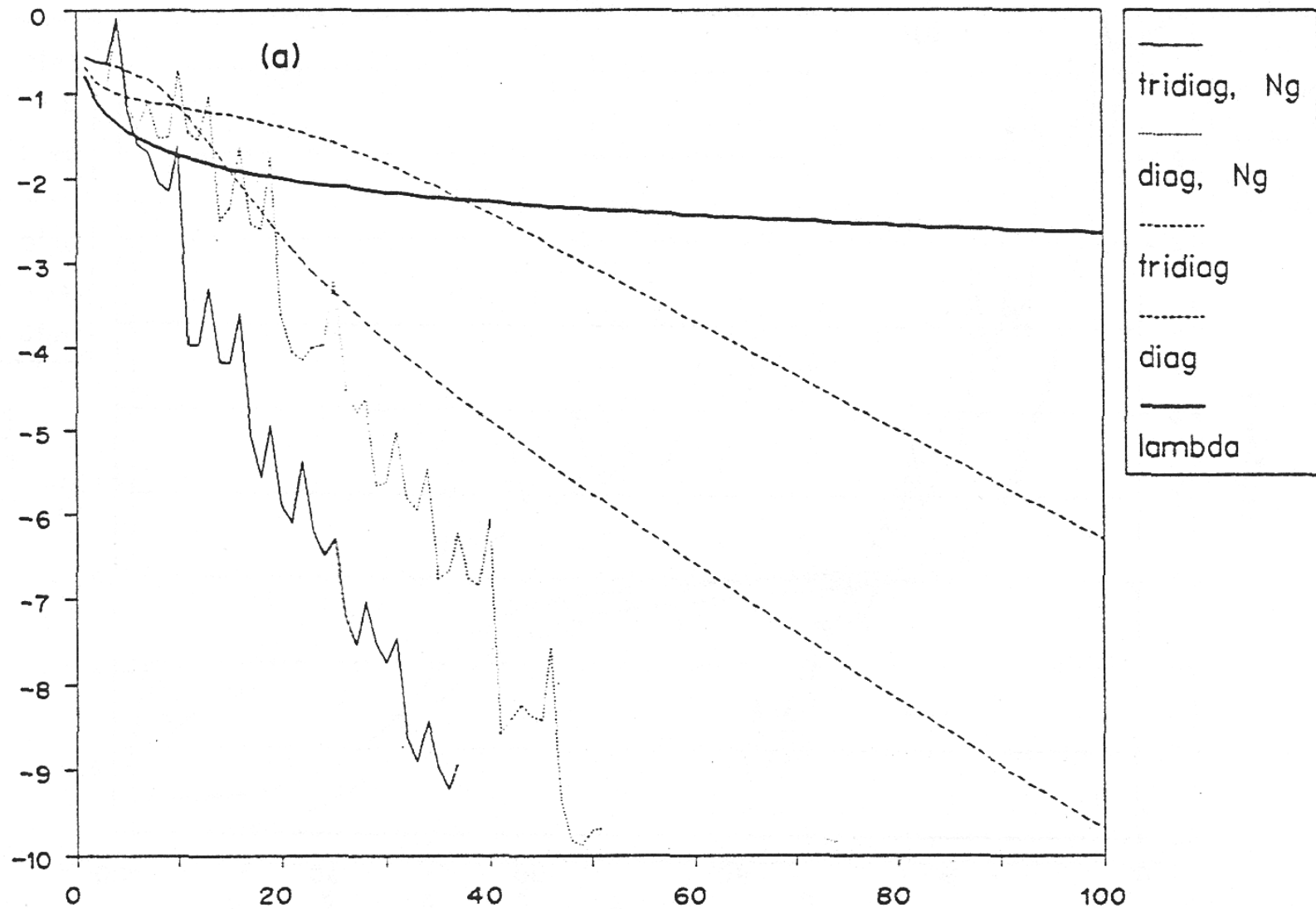
# constructing $\Lambda^*$

- basic idea:
  - set  $S = (0, \dots, 1, 0, \dots)$
  - perform FS
  - $\rightarrow$  delivers one column of  $\Lambda$  matrix
  - repeat for all spatial (radial) points
  - $\rightarrow$  compute  $\Lambda$  matrix
- if done like described  $\rightarrow$  very expensive!
- however, it can be done analytically!

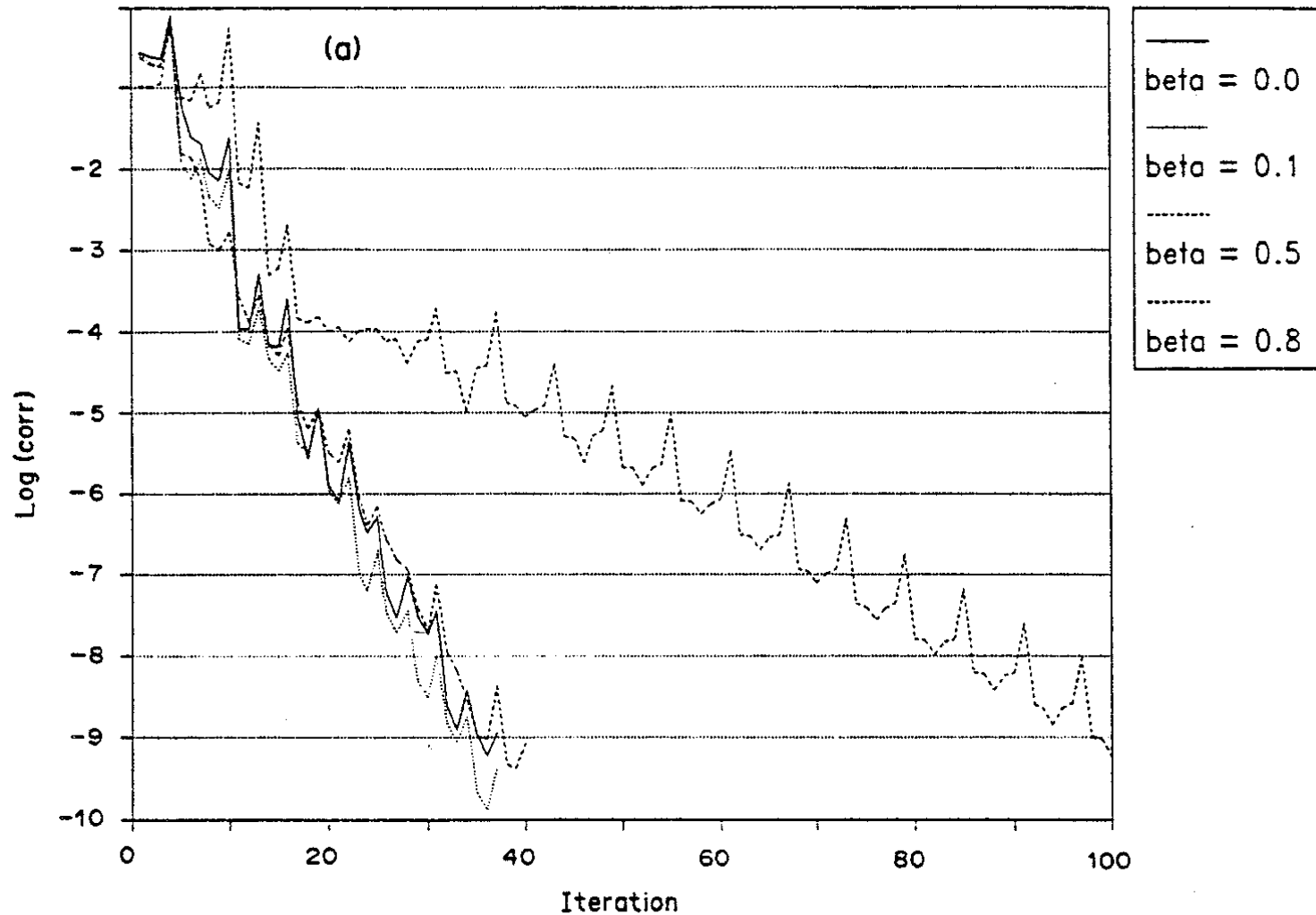
# constructing $\Lambda^*$

- can be extended to full  $\Lambda$  matrix!
- this method can also be used in moving media
- can be extended to line transfer (later)

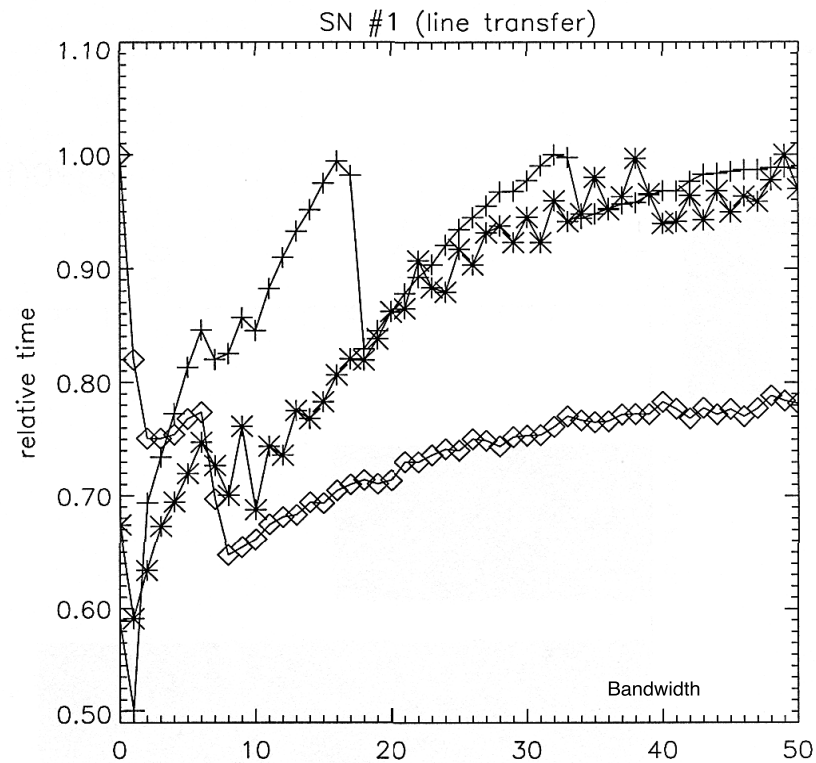
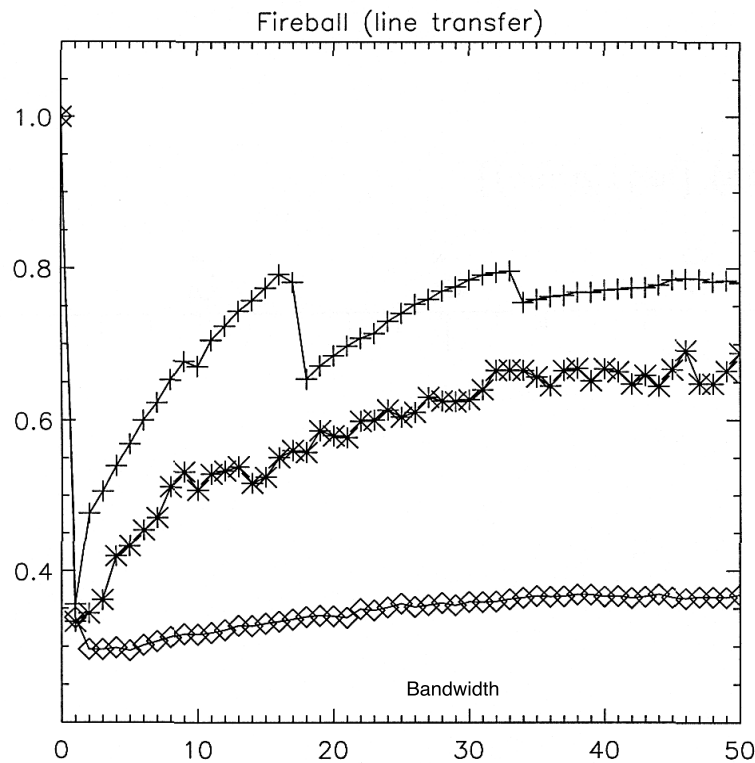
# Convergence: static



# Convergence: expanding

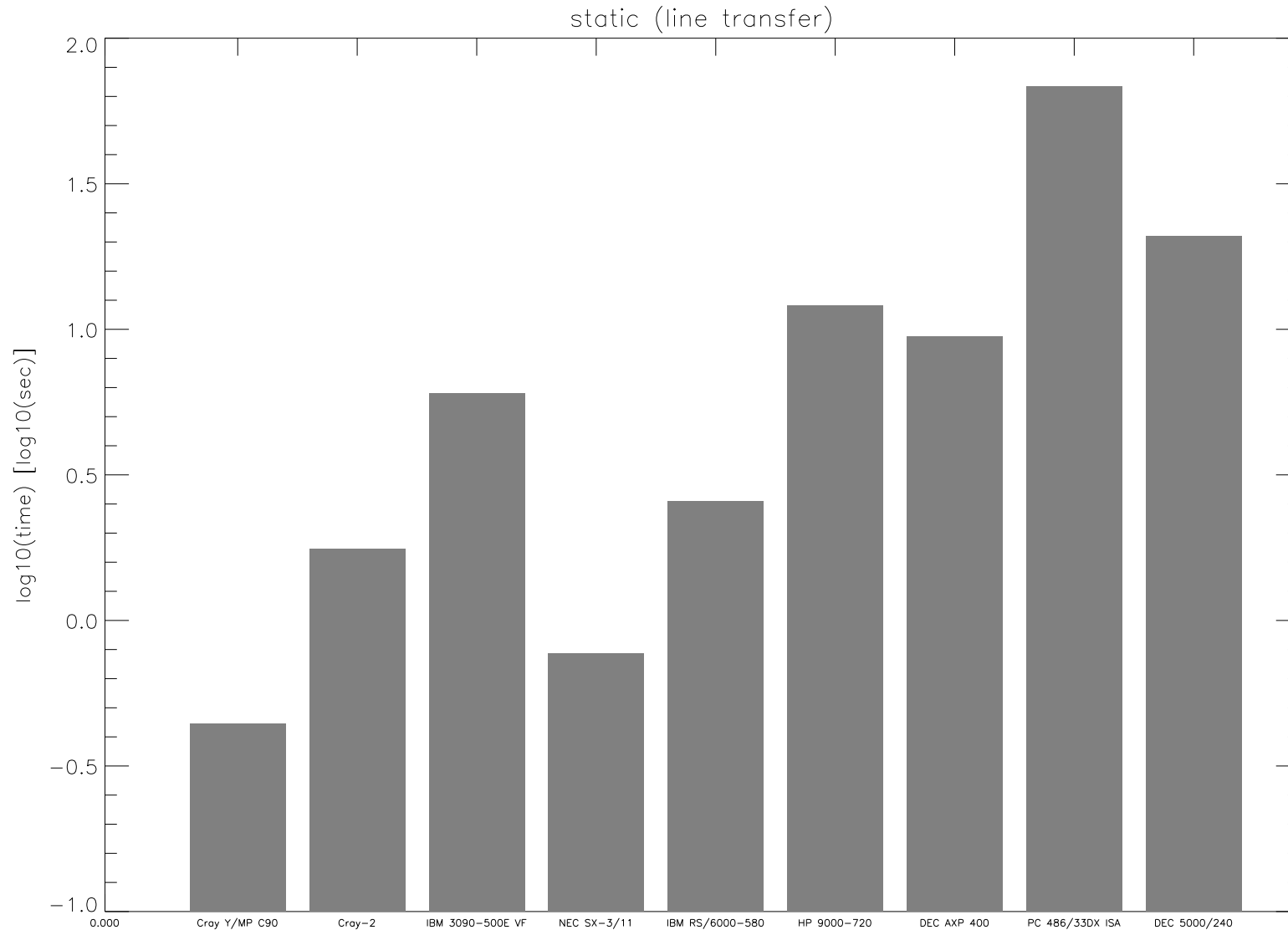


# relative Performance



- SN:  $v_{\max} = 0.13c$ , extension 100
- Fireball:  $v_{\max} = 0.9c$ , extension  $10^6$
- +: Cray Y/MP C90, \*: Cray-2,  
other: IBM 3090-500E VF

# relative Performance



● historical ... ca. 1993